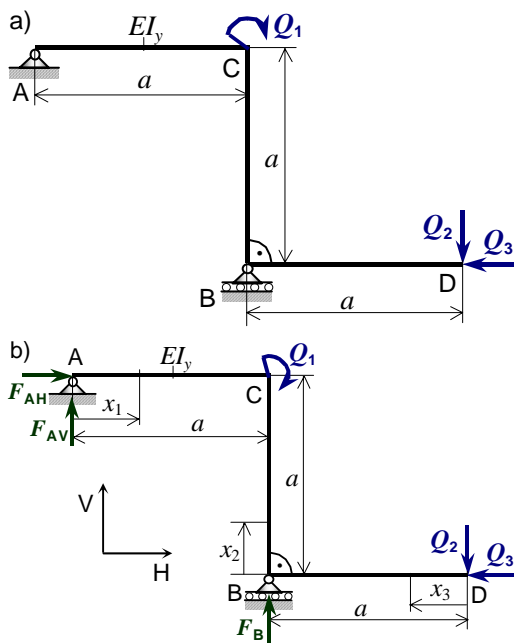


6. Primjer: Izračunavanje uplivnih koeficijenata za ravninski okvirni nosač



Za ravninski okvirni nosač ABCD zadan na slici a) treba odrediti uplivne koeficijente α_{ij} , za $i, j = 1, 2, 3$, uporabom drugog Castiglianovog poučka.

Zadano: $a, EI_y = \text{konst.}$

Rješenje:

Određivanje uplivnih koeficijenata uporabom drugog Castiglianovog poučka, kod konzolnog okvirnog nosača čiji dijelovi l_k , $k = 1, 2, 3$ imaju

$EI_y = \text{konst.}$, slijedi iz izraza:

$$\alpha_{ij} = \left(\frac{\partial U}{\partial Q_i} \right)_{Q_j=1} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{Q_j=1} \cdot \frac{\partial M_y(x_k)}{\partial Q_i} dx_k \right) \right].$$

Za određivanje momenata savijanja duž konture okvirnog nosača, potrebno je znati reakcije u osloncima A i B nosača kod opterećenja poopćenim silama Q_1, Q_2, Q_3 , slika b).

Reakcije u osloncima okvirnog nosača jesu:

$$\sum F_H = 0 \quad F_{AH} - Q_3 = 0 \rightarrow F_{AH} = Q_3,$$

$$\sum F_V = 0 \quad F_{AV} + F_B - Q_2 = 0,$$

$$\sum M_A = 0 \quad F_B \cdot a - Q_1 - Q_2 \cdot 2a - Q_3 \cdot a = 0 / : a$$

$$\text{Slijedi: } F_B = \frac{Q_1}{a} + 2Q_2 + Q_3, \quad F_A = Q_2 - F_B = -\frac{Q_1}{a} - Q_2 - Q_3.$$

Momenti savijanja duž konture nosača $M_b(x_k) = M_y(x_k)$ i potrebne derivacije jesu:

Momenti savijanja $M_y(x_k)$:	$\frac{\partial M_y(x_k)}{\partial Q_1}$	$\frac{\partial M_y(x_k)}{\partial Q_2}$	$\frac{\partial M_y(x_k)}{\partial Q_3}$
$M_y(x_1) = F_{AV} \cdot x_1 = -\frac{x_1}{a} Q_1 - Q_2 \cdot x_1 - Q_3 \cdot x_1$	$-\frac{x_1}{a}$	$-x_1$	$-x_1$
$M_y(x_2) = -Q_2 \cdot a - Q_3 \cdot x_2$	0	$-a$	$-x_2$
$M_y(x_3) = -Q_2 \cdot x_3$	0	$-x_3$	0

Uplivni koeficijenti nosača uporabom drugog Castiglianovog poučka jesu:

$$\alpha_{11} = \left(\frac{\partial U}{\partial Q_1} \right)_{\substack{Q_2=0 \\ Q_3=0}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{\substack{Q_2=0 \\ Q_3=0}} \cdot \frac{\partial M_y(x_k)}{\partial Q_1} dx_k \right) \right] = \frac{1}{EI_y} \int_0^a -\frac{x_1}{a} \cdot \left(-\frac{x_1}{a}\right) dx_1 = \frac{a}{3EI_y},$$

$$\alpha_{12} = \left(\frac{\partial U}{\partial Q_1} \right)_{\substack{Q_2=1 \\ Q_3=0}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{\substack{Q_2=1 \\ Q_3=0}} \cdot \frac{\partial M_y(x_k)}{\partial Q_1} dx_k \right) \right] = \frac{1}{EI_y} \int_0^a -x_1 \cdot \left(-\frac{x_1}{a}\right) dx_1 = \frac{a^2}{3EI_y} = \alpha_{21},$$

$$\alpha_{13} = \left(\frac{\partial U}{\partial Q_1} \right)_{\substack{Q_2=0 \\ Q_3=1}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} \cdot \frac{\partial M_y(x_k)}{\partial Q_1} dx_k \right) \right] = \frac{1}{EI_y} \int_0^a -\frac{x_1}{a} \cdot (-x_1) dx_1 = \frac{a^2}{3EI_y} = \alpha_{31},$$

$$\begin{aligned} \alpha_{22} &= \left(\frac{\partial U}{\partial Q_2} \right)_{\substack{Q_1=0 \\ Q_2=1 \\ Q_3=0}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{\substack{Q_1=0 \\ Q_2=1 \\ Q_3=0}} \cdot \frac{\partial M_y(x_k)}{\partial Q_2} dx_k \right) \right] = \\ &= \frac{1}{EI_y} \left[\int_0^a -x_1 \cdot (-x_1) dx_1 + \int_0^a -a \cdot (-a) dx_2 + \int_0^a -x_3 \cdot (-x_3) dx_3 \right] = \frac{5}{3} \cdot \frac{a^3}{EI_y}, \end{aligned}$$

$$\begin{aligned} \alpha_{23} &= \left(\frac{\partial U}{\partial Q_2} \right)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} \cdot \frac{\partial M_y(x_k)}{\partial Q_2} dx_k \right) \right] = \\ &= \frac{1}{EI_y} \left[\int_0^a -x_1 \cdot (-x_1) dx_1 + \int_0^a -x_2 \cdot (-a) dx_2 \right] = \frac{5}{6} \cdot \frac{a^3}{EI_y} = \alpha_{32}, \end{aligned}$$

$$\begin{aligned} \alpha_{33} &= \left(\frac{\partial U}{\partial Q_3} \right)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} \cdot \frac{\partial M_y(x_k)}{\partial Q_3} dx_k \right) \right] = \\ &= \frac{1}{EI_y} \left[\int_0^a -x_1 \cdot (-x_1) dx_1 + \int_0^a -x_2 \cdot (-x_2) dx_2 \right] = \frac{2}{3} \cdot \frac{a^3}{EI_y}. \end{aligned}$$