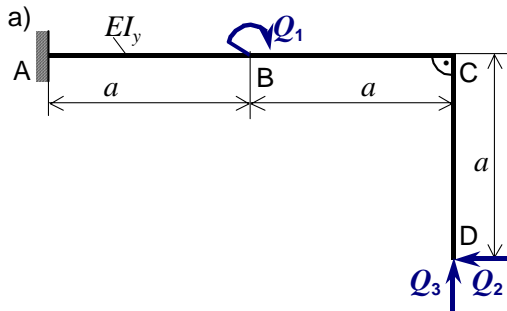


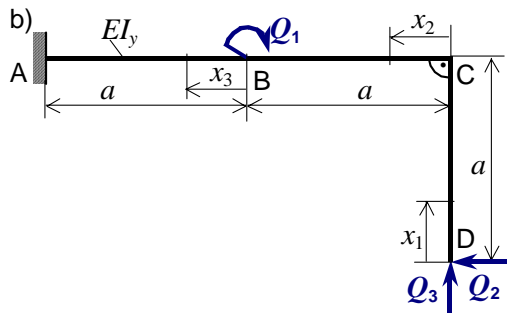
4. Primjer: Izračunavanje uplivnih koeficijenata za ravninski konzolni okvirni nosač



Za ravninski konzolni okvirni nosač ABCD zadan na slici a) treba odrediti uplivne koeficijente α_{ij} , za $i, j = 1, 2, 3$, uporabom drugog Castiglianovog poučka.

Zadano: $a, EI_y = \text{konst.}$

Rješenje:



Određivanje uplivnih koeficijenata uporabom drugog Castiglianovog poučka, kod konzolnog okvirnog nosača čiji dijelovi l_k , $k = 1, 2, 3$ imaju

$EI_y = \text{konst.}$, slijedi iz izraza:

$$\alpha_{ij} = \left(\frac{\partial U}{\partial Q_i} \right)_{Q_j=1} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{Q_j=1} \cdot \frac{\partial M_y(x_k)}{\partial Q_i} dx_k \right) \right].$$

Momenti savijanja duž konture nosača $M_b(x_k) = M_y(x_k)$ i potrebne derivacije jesu:

Momenti savijanja $M_y(x_k)$:	$\frac{\partial M_y(x_k)}{\partial Q_1}$	$\frac{\partial M_y(x_k)}{\partial Q_2}$	$\frac{\partial M_y(x_k)}{\partial Q_3}$
$M_y(x_1) = -Q_2 \cdot x_1$	0	$-x_1$	0
$M_y(x_2) = -Q_2 \cdot a + Q_3 \cdot x_2$	0	$-a$	x_2
$M_y(x_3) = -Q_1 - Q_2 \cdot a + Q_3 \cdot (a + x_3)$	-1	$-a$	$(a + x_3)$

Uplivni koeficijenti nosača uporabom drugog Castiglianovog poučka jesu:

$$\alpha_{11} = \left(\frac{\partial U}{\partial Q_1} \right)_{\substack{Q_1=1 \\ Q_2=0 \\ Q_3=0}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{Q_j=1} \cdot \frac{\partial M_y(x_k)}{\partial Q_1} dx_k \right) \right] = \frac{1}{EI_y} \int_0^a -1 \cdot (-1) dx_3 = \frac{a}{EI_y},$$

$$\alpha_{12} = \left(\frac{\partial U}{\partial Q_1} \right)_{\substack{Q_1=0 \\ Q_2=1 \\ Q_3=0}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{Q_j=0} \cdot \frac{\partial M_y(x_k)}{\partial Q_1} dx_k \right) \right] = \frac{1}{EI_y} \int_0^a -a \cdot (-1) dx_3 = \frac{a^2}{EI_y} = \alpha_{21},$$

$$\alpha_{13} = \left(\frac{\partial U}{\partial Q_1} \right)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{Q_j=0} \cdot \frac{\partial M_y(x_k)}{\partial Q_1} dx_k \right) \right] = \frac{1}{EI_y} \int_0^a (a + x_3) \cdot (-1) dx_3 = -\frac{3}{2} \cdot \frac{a^2}{EI_y} = \alpha_{31},$$

$$\alpha_{22} = \left(\frac{\partial U}{\partial Q_2} \right)_{\substack{Q_1=0 \\ Q_2=1 \\ Q_3=0}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \left(\int_0^{l_k} M_y(x_k)_{Q_j=0} \cdot \frac{\partial M_y(x_k)}{\partial Q_2} dx_k \right) \right] =$$

$$= \frac{1}{EI_y} \left[\int_0^a -x_1 \cdot (-x_1) dx_1 + \int_0^a -a \cdot (-a) dx_2 + \int_0^a -a \cdot (-a) dx_3 \right] = \frac{7}{3} \cdot \frac{a^3}{EI_y},$$

$$\alpha_{23} = \left(\frac{\partial U}{\partial Q_2} \right)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \int_0^{l_k} M_y(x_k)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} \cdot \frac{\partial M_y(x_k)}{\partial Q_2} dx_k \right] =$$

$$= \frac{1}{EI_y} \left[\int_0^a x_2 \cdot (-a) dx_2 + \int_0^a (a+x_3) \cdot (-a) dx_3 \right] = -2 \cdot \frac{a^3}{EI_y} = \alpha_{32},$$

$$\alpha_{33} = \left(\frac{\partial U}{\partial Q_3} \right)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} = \frac{1}{EI_y} \left[\sum_{k=1}^3 \int_0^{l_k} M_y(x_k)_{\substack{Q_1=0 \\ Q_2=0 \\ Q_3=1}} \cdot \frac{\partial M_y(x_k)}{\partial Q_3} dx_k \right] =$$

$$= \frac{1}{EI_y} \left[\int_0^a x_2 \cdot x_2 dx_2 + \int_0^a (a+x_3) \cdot (a+x_3) dx_3 \right] = \frac{8}{3} \cdot \frac{a^3}{EI_y}.$$